## PhD Preliminary Written Exam Control Systems Fall 2015

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There are two Parts, assigned 2 point each, for a total of 4 points.

## Part I (2 points):

A feedback system is shown in Figure 1 where P(s) is a system model and  $e^{-\tau s}$  represents transmission delay in the feedback path. The system is open loop stable and its transfer func-



Figure 1: Feedback system.

tion can be fairly accurately modeled over the range of frequencies that are relevant to stability analysis by

$$G(s) = \sqrt{\frac{\sqrt{2}}{s+1}}$$

for  $s = j\omega$  with  $\omega$  measured in radians/sec. It is noted that the system model does have a rational transfer function, and hence it does not have a finite-dimensional state representation.

## **Complete/answer the following:**

i) Draw the Bode plot for the open loop transfer function (approximately).

ii) Draw the Nyquist plot.

iii) Explain why the closed loop system is stable for zero time-delay  $\tau = 0$ .

iv) What is the maximal interval  $[0, \tau_{max})$  for the time-delay in the feedback loop for which the closed loop system remains stable.

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## Part II (2 points):

Consider two  $n \times n$  real matrices A and  $\Delta$ .

i) Consider the autonomous linear dynamical system

$$\dot{x}(t) = (A + \Delta) x(t),$$

with initial conditions  $x(0) = x_0$ . Show that provided  $A\Delta = \Delta A$ , the solution is given by

 $e^{\Delta t}e^{At}x_0.$ 

ii) Give an example of two matrices A,  $\Delta$  such that  $A\Delta \neq \Delta A$ .

iii) Let 
$$A = \begin{bmatrix} -1 & 0 \\ 0 & -2 \end{bmatrix}$$
 and  $\Delta = \begin{bmatrix} 0 & \delta_2 \\ \delta_1 & 0 \end{bmatrix}$ 

- Determine the conditions that the positive scalars  $\delta_1$  and  $\delta_2$  have to satisfy to guarantee stability of the above system.
- Set  $\delta_2 = 0$  and find the solution to the above system for the initial condition  $x_0 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ .
- Set  $\delta_2 = 0$  and consider the system with the input u and the output y

$$\dot{x}(t) = (A + \Delta) x(t) + B u(t)$$
  
$$y(t) = C x(t)$$

where  $B = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$  and  $C = \begin{bmatrix} 0 & 1 \end{bmatrix}$ .

How does the peak value on the Bode magnitude plot of the transfer function (from u to y) depend on  $\delta_1$ ? At what frequency does this peak value take place?